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MEASURING THE GLOBAL PHASE COHERENCE OF AN IMAGE

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ABSTRACT

The Fourier phase spectrum of an image is well known to contain crucial information about the image geometry, in particular its contours. In this paper, we show that it is also strongly related to the image quality, in particular its sharpness. We propose a way to define the Global Phase Coherence (GPC) of an image, by estimating the volume of all possible phase functions that, associated with the measured modulus, produce images that are not less likely than the original image. The likelihood is measured with the total variation (Rudin-Osher-Fatemi implicit prior), and the numerical estimation is realized by a Monte-Carlo simulation. We show that the obtained GPC measure decreases with blur, noise, and ringing, and thus provides a new interesting sharpness indicator, that can be used for parametric blind deconvolution, as demonstrated by experiments.

Index Terms— Fourier Transform, phase information, image quality, sharpness, total variation.

1. INTRODUCTION

The Fourier Transform of an image can be decomposed in two components, its power spectrum (the square modulus of each Fourier coefficient), and the phase (the argument of each Fourier coefficient). While the modulus is pretty well understood in terms of image filtering (many smoothing filter have a positive Fourier Transform, so that they only operate on the modulus component), the phase component seems to be much more complex. Oppenheim and Lim [1] have noticed that this phase component is responsible for the formation of geometrical image elements like contours, since these elements persist when the modulus information is lost (e.g., when a constant modulus is imposed, or when the power spectrum of another image is used). Morrone and Owens [2] have shown that edges could be efficiently detected on an image by looking at points of maximum phase congruency. Later, Kovess [3] improved the measure of phase congruency, by adding noise compensation and multiscale capabilities, yielding a more robust low-level image invariant. More recently, Wang and Simoncelli [4] defined a notion of local phase coherence based on the coarse-to-fine prediction across scales of the phase of a wavelet transform, and showed its relation

to image blur. Because the translation of an image can be characterized by the addition of a ramp function in the phase domain, phase information has also been used for image registration, in early studies [5] but also more recently, e.g. in [6] to provide a motion confidence measure. Let us also mention recent psychophysical studies [7, 8], which suggest that the phase component plays a specific role in human perception.

Phase coherence is a requirement for contours, because all sine waves involved in the reconstruction of an image from its Fourier coefficients have to cooperate locally to produce a high gradient between two rather “flat” regions. Hence, measuring the total amount of phase coherence of an image may provide an indication on the quality of these transitions between flat regions, that is, more intuitively, on the image sharpness. In Section 2, we propose a definition of the Global Phase Coherence (GPC) of an image, by considering the relative regularity (total variation) of images with all possible phase functions. In Section 3, we describe a Monte Carlo algorithm to estimate the GPC, and give a solution to prevent the usual quantization of images and the implicit periodization (due to the use of the Discrete Fourier Transform) from introducing a strong bias. In Section 4, we study the behavior of GPC with respect to noise and blur and give theoretical and experimental arguments to demonstrate that the GPC of an image is related to its sharpness. This leads us to an application to parametric blind deconvolution (Section 5), motivated by the fact that ringing also decreases the GPC, contrary to many sharpness indicators. In Section 6, we conclude and mention some possible other applications.

2. A GLOBAL PHASE COHERENCE MEASURE

Let $u : \Omega \rightarrow \mathbb{R}$ be a discrete grey-level image, where $\Omega = \{0, \dots, n-1\}^2$ is the discrete image domain (we assume that Ω is a square to simplify the notations) and $u(\mathbf{x})$ represents the intensity of a pixel $\mathbf{x} \in \Omega$. The Discrete Fourier Transform (DFT) of u is the complex-valued function

$$\hat{u}(\xi) = \sum_{\mathbf{x} \in \Omega} u(\mathbf{x}) e^{-\frac{2i\pi}{n} \langle \mathbf{x}, \xi \rangle}$$

defined on $R = \mathbb{Z}^2 \cap [-\frac{n}{2}, \frac{n}{2})^2$, and the phase of u is a function $\varphi : R \rightarrow S^1$ such that $\hat{u}(\xi) = |\hat{u}(\xi)| \cdot e^{i\varphi(\xi)}$. Since

u is real-valued, φ is odd, that is $\varphi(-\xi) = -\varphi(\xi)$ for all $\xi \in R$. To understand the nature of the information contained in φ , we can change φ into another (odd) phase function ψ and look at the reconstructed image

$$u_\psi(\mathbf{x}) = \frac{1}{n^2} \sum_{\xi \in R} |\hat{u}(\xi)| \cdot e^{\frac{2i\pi}{n} \langle \mathbf{x}, \xi \rangle + i\psi(\xi)}.$$

We distorted the phase function φ of the classical Lacornou image (see Fig. 1) by adding to it a random shift εS , yielding a new phase function $\psi = \varphi + \varepsilon S$, where ε is a fixed number ($\varepsilon = 0.2$ on the experiment) and the S function is made of i.i.d. random variables uniformly distributed on $(-\pi, \pi)$ (except for half of the variables, which are constrained by the fact that S must be an odd function). As we can see on Fig. 1, when the phase information is deteriorated, the first structures to be damaged are flat zones. In the extreme case ($\varepsilon = 1$), the phase would become completely random, and we would obtain a microtexture (colored noise). To measure the amount of “image structure” that is contained in the phase component φ , we propose to use a likelihood measurement based on total variation: the probability density function $p(u) = Z^{-1} \exp(-\alpha TV(u))$, where Z and α are positive constants, and the (periodic) total variation of u is

$$TV(u) = \sum_{|\mathbf{x}-\mathbf{y}|=1} |u(\mathbf{x}) - u(\mathbf{y})|, \quad (1)$$

(the difference $\mathbf{x}-\mathbf{y}$ being understood modulo Ω). This image prior has been implicitly used for a long time, since it naturally arises when the Rudin-Osher-Fatemi denoising model [9] is rewritten in a statistical (maximum a posteriori) setting.

Among all possible odd phase functions ψ , some of them will produce a more likely image ($p(u_\psi) > p(u)$), while most of them will produce a less likely image ($p(u_\psi) < p(u)$). Since $p(u)$ is a decreasing function of $TV(u)$, we can as well compare $TV(u_\psi)$ and $TV(u)$, and obtain the following definition:



original Lacornou image
TV = 19.76

after phase shift ($\varepsilon = 0.2$)
TV = 22.47

Fig. 1. The phase function of the Lacornou image (left) is altered by a random phase shift in $(-\varepsilon\pi, \varepsilon\pi)$ which pollutes flat zones and increases the total variation (right).

Definition 1 We define the global phase coherence (GPC) of an image u by

$$GPC(u) = -\log_{10} \left(\frac{|\{\psi \in \mathcal{P}, TV(u_\psi) \leq TV(u)\}|}{|\mathcal{P}|} \right),$$

where \mathcal{P} is the vector space of odd phase functions and $|S|$ denotes the Lebesgue measure of a set S .

Hence, the global phase coherence of an image is, in -log scale, the relative volume of phase functions that, combined with the modulus $|\hat{u}|$, produce images that are not less plausible than u . Notice that for a 100×100 image, a precision of 10% on each phase component leads to a relative volume of about 10^{-5000} , so that we expect the \log_{10} scale to be more convenient to measure the global phase coherence.

3. NUMERICAL ESTIMATION

A classical way to estimate numerically the relative volume of a set is to use Monte Carlo sampling. Here we could take N images u_1, \dots, u_N generated by imposing random phases to u , and count the number k of indices i for which $TV(u_i) \leq TV(u)$. Then we would have $GPC(u) \simeq -\log_{10}(k/N)$. However, this method cannot be used here, since we expect $GPC(u)$ to be large (several hundreds or thousands) and in such cases we would systematically obtain $k = 0$. To overcome this difficulty, we numerically define the global phase coherence of u by

$$GPC_N(u) = -\log_{10} \Phi \left(\frac{\mu - TV(u)}{\sigma} \right),$$

where μ and σ are the empirical mean and variance of the samples $(TV(u_i))_{1 \leq i \leq N}$, and Φ is the tail of the Normal Distribution, that is $\Phi(x) = (2\pi)^{-1/2} \int_x^{+\infty} e^{-t^2/2} dt$. This approximation amounts to assume that if U is a random image with fixed Fourier modulus and i.i.d uniform (odd) random phases, then the distribution of $TV(U)$ is Gaussian. This assumption can be proven to be asymptotically true (using a generalization of the Central Limit Theorem), and was always verified in practice up to a precision of 10^{-4} or so (maximum $\|\cdot\|_\infty$ difference between repartition functions).

Since we compute the phase functions with a Discrete Fourier Transform, we implicitly assume that all discrete images are periodic, and this is why we chose to use a periodic definition of $TV(u)$ (Equation 1). However, it is well known that the forced periodization of an image creates strong artifacts on its Fourier Transform, especially among vertical and horizontal frequencies. This could bias the GPC measure (and numerical experiments prove that it actually does), so in order to avoid this we work on the periodic component of u (see [10]), $\text{per}(u)$, whose reduced discontinuities across the frame border permits to avoid periodization artifacts. Another artifact that could (and actually does) bias the GPC measure is

the fact that numerical images are quantized on a finite number of grey values, which introduces a small bias on the TV measure (e.g., quantization may produce artificially constant zones where $TV = 0$). In order to avoid this, we apply a dequantization operator Q , that simply consists in a $(1/2, 1/2)$ Fourier-based translation [11]. In the end, we are led to estimate the global phase coherence of a numerical image by $GPC'_N(u) = GPC_N(Q(\text{per}(u)))$ for N large enough (one thousand or more).

4. GPC AS A SHARPNESS INDICATOR

Now we have defined the GPC in a natural way and dealt with numerical artifacts, we can try to understand how the GPC measure is related to image properties. A first simple remark is that it is invariant under affine contrast changes, that is one has $GPC(a \cdot u + b) = GPC(u)$ for any real a and b such that $a \neq 0$. Another interesting property is that if U is a colored noise (that is, a white noise convolved with some given kernel), then one has $\text{Prob}\{GPC(U) \geq t\} \leq 10^{-t}$. In other words, it is almost impossible for a noise image to have, by chance, a GPC above 3 or 4.

Previous remarks suggest that the GPC should be related to the level of blur. On Fig. 2, we estimated the GPC of several small windows, and it appeared to distinguish very well foreground (sharp) and background (blurry) zones.

To investigate further the relation between GPC, blur and noise, we can compute the 2D-function

$$f(r, \sigma) = GPC'_N(g_r \star u + \sigma W),$$

where g_r is the 2-D Gaussian kernel with standart deviation r and W a white noise image with unit variance. On Fig. 3,

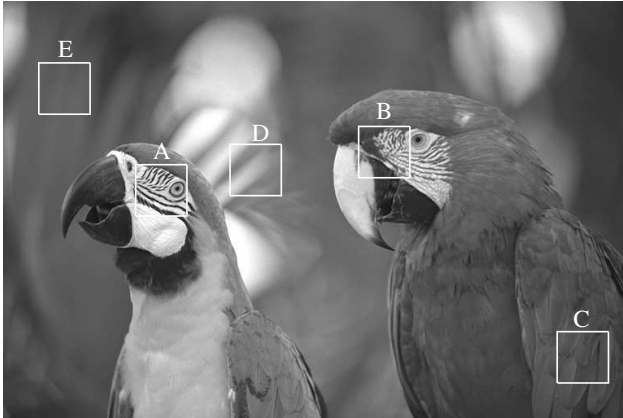


Fig. 2. Estimated GPC on several sub-windows of the *parrots* image [12] are 206 (A), 388 (B), 240 (C), 2.56 (D), 0.33 (E). We can see that the GPCs of all three well-focused details (A,B,C) are very high, independently of their content or contrast. Background windows are blurry and hence have very low GPCs.

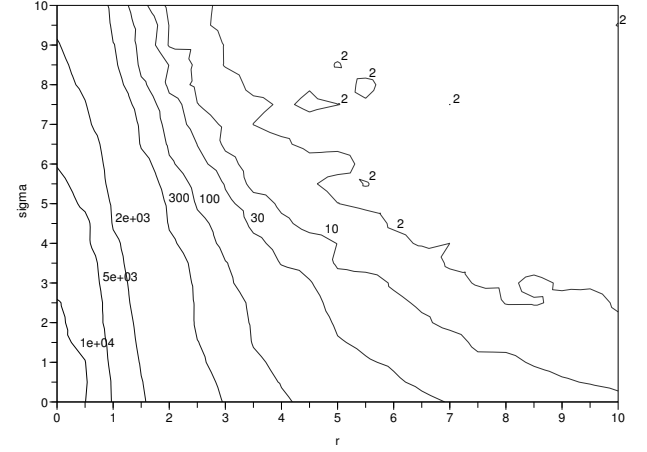


Fig. 3. 2D blur-noise GPC diagram for Lacornou image. GPC_N is computed for $N = 4000$.

the level-lines of f are represented for the classical Lacornou image (u): we can see that the GPC rapidly decreases when the blur and the noise increase, and that, for example, a blur of $r = 1$ is, in terms of GPC, equivalent to a noise of $\sigma = 6$.

From these observations, the GPC appears to be some kind of sharpness indicator for natural images. One can try to explain this in the following way: a natural image generally presents edges and flat zones. When its phase is modified, the sine waves that were perfectly aligned to produce these edges and flat zones are desynchronized, so that wavy patterns appear in flat zones, which increases the total variation. This phenomenon is amplified for sharp images, that have sharp edges near flat zones, but reduced for blurry and/or noisy images, that are more robust to slight phase distortions.

5. APPLICATION TO BLIND DECONVOLUTION

Contrary to what common sense would suggest, “sharp” is not the opposite of “blurry”, in the sense that an image which is not blurry is not necessarily sharp: it can present quantity of other artifacts like noise, ringing, aliasing, etc., that, like blur, reduce the amount of true details that can be perceived. Up to now, we checked that the GPC was decreased by blur and noise, but is it also decreased by ringing? Ringing is typically produced on an image when some components of its Fourier Transform are improperly magnified, which causes oscillations in the space domain. Intuitively, we can expect ringing to decrease the GPC, since oscillations are known to have a high TV cost. This suggests an application of the GPC measure to blind deconvolution: if an image u has been obtained by convolving a given image v with some Gaussian kernel g_r for some (unknown) r , we could try to estimate r (and v) by selecting the sharpest image among all deconvolved images $(g_r^{-1} \star u)_{r>0}$. This experiment is illustrated on Fig. 4 on the Lacornou image and on a degraded version of it: the GPC of

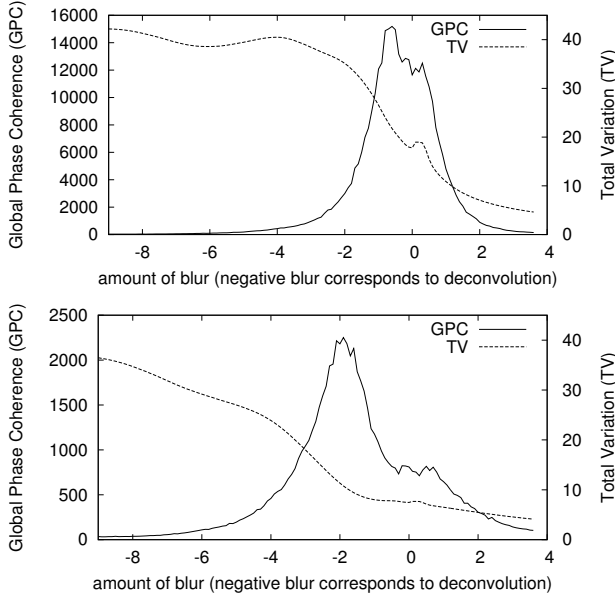


Fig. 4. Top: Graphs of $r \mapsto GPC(h_r \star u)$ and $r \mapsto TV(h_r \star u)$, where u is the Lacornou image and h_r is a deconvolution kernel ($r < 0$) or a blur kernel ($r > 0$) (see Equation 2). Bottom: same experiment applied to $u' = g_2 \star u + w$, where w is a Gaussian white noise with unit variance. Contrary to a simple TV measurement, the GPC permits to select the best deconvolution parameter r as the one producing the image with the most coherent phases. The original Lacornou image can be slightly improved (GPC is maximum for $r = -0.6$), and the parameter of the blur kernel used to produce the degrade version is well recovered (GPC is maximum for $r = -2.1$).

$h_r \star u$ is represented as a function of r , where $h_r = g_r$ for $r \geq 0$ (convolution) and

$$\widehat{h_r}(\xi) = \frac{\widehat{g_{-r}}^*(\xi)}{|\widehat{g_{-r}}(\xi)|^2 + \lambda\pi^2|\xi|^2} \quad (2)$$

with $\lambda = 0.1$ for $r < 0$ (regularized deconvolution). In each case, the deconvolution parameter (r) that is found by maximizing the GPC of the restored image is near the expected value: a little less than 0 for the original image (since, like most images, its quality can be improved with a small deconvolution), and around -2 for the degraded image (that had been blurred with $r = 2$). Notice that classical energy-based criteria (L^2 norm, TV, etc.) lead to (approximately) monotone graphs and thus offer no such possibility to select r .

6. CONCLUSION

We presented a way to analyze the phase coherence of an image, by using both its Fourier Transform and a spatial measurement, the Total Variation. We showed that the phase coherence could be analyzed globally, provided that artifacts

are avoided by using a periodic+smooth decomposition [10] and a dequantization process [11]. The resulting GPC measurement decreases with blur, noise and ringing, and seems for these reasons to be an interesting indicator of the quality (sharpness) of an image. We showed that it could be used for local blur evaluation and parametric blind deconvolution, but, among other applications that could be investigated, image quality assessment, the selection of sharp images in large databases or acquisition campaigns, and more general image restoration processes seem to offer interesting perspectives.

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